

EE301ES: ENGINEERING MECHANICS

II Year B.Tech. EEE I-Sem

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Prerequisites: Nil

Course Objectives: The objectives of this course are to

- Explain the resolution of a system of forces, compute their resultant and solve problems using equations of equilibrium
- Perform analysis of bodies lying on rough surfaces.
- Locate the centroid of a body and compute the area moment of inertia and mass moment of inertia of standard and composite sections
- Explain kinetics and kinematics of particles, projectiles, curvilinear motion, centroidal motion and plane motion of rigid bodies.
- Explain the concepts of work-energy method and its applications to translation, rotation and plane motion and the concept of vibrations

Course Outcomes: At the end of the course, students will be able to

- Determine resultant of forces acting on a body and analyse equilibrium of a body subjected to a system of forces.
- Solve problem of bodies subjected to friction.
- Find the location of centroid and calculate moment of inertia of a given section.
- Understand the kinetics and kinematics of a body undergoing rectilinear, curvilinear, rotatory motion and rigid body motion.
- Solve problems using work energy equations for translation, fixed axis rotation and plane motion and solve problems of vibration.

UNIT - I

Introduction to Engineering Mechanics - Force Systems: Basic concepts, Particle equilibrium in 2-D & 3-D; Rigid Body equilibrium; System of Forces, Coplanar Concurrent Forces, Components in Space – Resultant- Moment of Forces and its Application; Couples and Resultant of Force System, Equilibrium of System of Forces, Free body diagrams, Equations of Equilibrium of Coplanar Systems and Spatial Systems; Static Indeterminacy

UNIT - II

Friction: Types of friction, Limiting friction, Laws of Friction, Static and Dynamic Friction; Motion of Bodies, wedge friction, screw jack & differential screw jack;
Centroid and Centre of Gravity -Centroid of Lines, Areas and Volumes from first principle, centroid of composite sections; Centre of Gravity and its implications. – Theorem of Pappus

UNIT - III

Area moment of inertia- Definition, Moment of inertia of plane sections from first principles, Theorems of moment of inertia, Moment of inertia of standard sections and composite sections; Product of Inertia, Parallel Axis Theorem, Perpendicular Axis Theorem

Mass Moment of Inertia: Moment of Inertia of Masses - Transfer Formula for Mass Moments of Inertia – Mass moment of inertia of composite bodies.

UNIT - IV

Review of particle dynamics- Rectilinear motion; Plane curvilinear motion (rectangular, path, and polar coordinates). 3-D curvilinear motion; Relative and constrained motion; Newton's 2nd law (rectangular, path, and polar coordinates). Work-kinetic energy, power, potential energy. Impulse-momentum (linear, angular); Impact (Direct and oblique).

UNIT - V

Kinetics of Rigid Bodies -Basic terms, general principles in dynamics; Types of motion, Instantaneous centre of rotation in plane motion and simple problems; D'Alembert's principle and its applications in plane motion and connected bodies; Work Energy principle and its application in plane motion of connected bodies; Kinetics of rigid body rotation.

TEXT BOOKS:

1. Shames and Rao (2006) , Engineering Mechanics, Pearson Education
2. Reddy Vijay Kumar K. and J. Suresh Kumar (2010), Singer's Engineering Mechanics – Statics & Dynamics

REFERENCE BOOKS:

1. Timoshenko S.P and Young D.H., "Engineering Mechanics", McGraw Hill International Edition, 1983.
2. Andrew Pytel, Jaan Kiusalaas, "Engineering Mechanics", Cengage Learning, 2014.
3. Beer F.P & Johnston E.R Jr. Vector, "Mechanics for Engineers", TMH, 2004.
4. Hibbeler R.C & Ashok Gupta, "Engineering Mechanics", Pearson Education, 2010.
5. Tayal A.K., "Engineering Mechanics – Statics & Dynamics", Umesh Publications, 2011.
6. Basudeb Bhattacharyya, "Engineering Mechanics", Oxford University Press, 2008.
7. Meriam. J. L., "Engineering Mechanics", Volume-II Dynamics, John Wiley & Sons, 2008.